

An efficient algorithm to compute the minimum free energy of interacting nucleic acid strands

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We give the first polynomial time algorithm for predicting optimal multistranded structures, answering the open problem from Dirks, Bois, Schaeffer, Winfree and Pierce [SIAM Review 2007].

Practitioners need algorithms to predict the most favoured DNA/RNA secondary structures, called minimum free energy (MFE) structures, or to compute a partition function that allows assigning a probability to any structure. MFE prediction is NP-hard in the presence of pseudoknots—base pairings that violate a restricted planarity condition. However, for single-stranded unspseudoknotted structures, there are polynomial time dynamic programming algorithms. For multiple strands, the problem is significantly more complicated: Codon, Hajiaghayi and Thachuk [DNA27, 2021] proved it NP-hard for N bases and $\mathcal{O}(N)$ strands. In 2007, Dirks et al gave a polynomial time partition function algorithm for multiple ($\mathcal{O}(1)$) strands, now widely-used in software packages like NUPACK and ViennaRNA, however their technique did not generalise to MFE which they left open.

We give an $\mathcal{O}(N^4)$ time algorithm for unpseudoknotted multiple ($\mathcal{O}(1)$) strand MFE prediction [Shalaby, Woods, ICALP 2025], answering the open problem from Dirks et al. The challenge lies in considering the rotational symmetry of secondary structures, a global feature not immediately amenable to local subproblem decomposition used in dynamic programming. Our proof has two main technical contributions: First, a characterisation of symmetric secondary structures implying only quadratically many need to be considered when computing the rotational symmetry penalty. Second, that bound is leveraged by a backtracking algorithm to efficiently find the MFE in an exponential space of contenders.

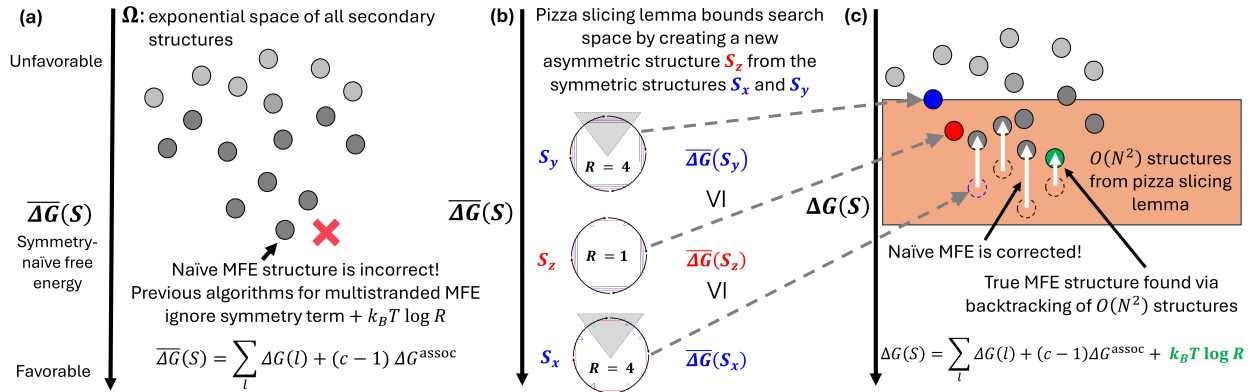


Figure 1: Overview of our result. (a) Current state-of-the-art MFE prediction algorithms for $\mathcal{O}(1)$ interacting strands are not guaranteed to predict the optimal MFE structure since they ignore the rotational symmetry penalty [Dirks et al, 2007; NUPACK; ViennaRNA]. (b) Slicing and swapping strategy for constructing new asymmetric structure S_z by combining two symmetric structures S_x, S_y that have the same symmetric backbone cut. (c) The slicing and swapping strategy guarantees efficient and correct MFE prediction within a backtracking subspace of $\mathcal{O}(N^2)$ structures.